Differential privacy without a central database

Boston Differential Privacy Summer School, 6-10 June 2022

Uri Stemmer

About this course

- The local model \checkmark
- The shuffle model \checkmark
- Streaming/online settings
- Differential privacy as a tool

Streaming/online settings Today's Outline



2. Privacy under continual observation







































































What is Streaming?

Correct answer: 9

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Alon, Matias, Szegedy 96

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- A stream of length n over domain X is a sequence of updates $(x_1, ..., x_n)$ where $x_i \in X$
- Let $g: X^* \to R$ be a function
- At every time $i \in [n]$ we obtain x_i
- At the end of the stream we need to output $z \approx g(x_1, ..., x_n)$
- Requirement: small space

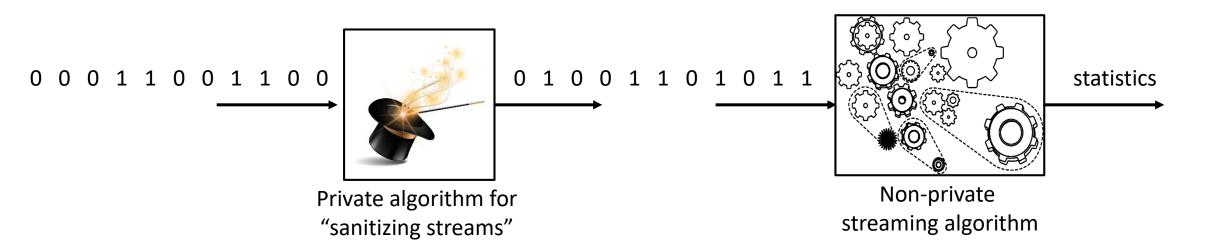
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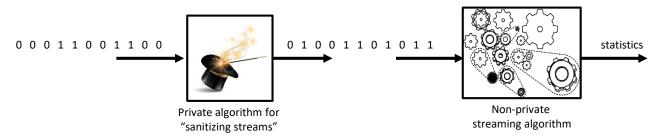
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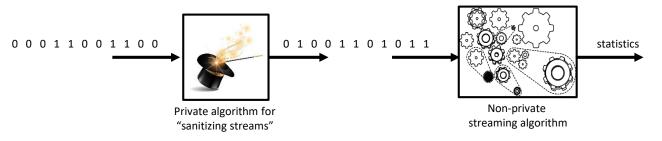
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- What does it mean for a streaming algorithm to be DP?

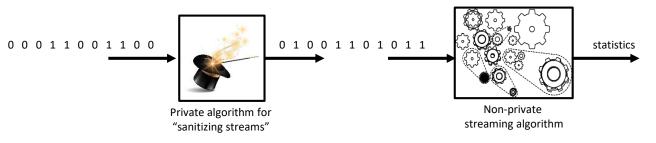
A streaming algorithm \mathcal{A} is (ε, δ) -DP if for any two neighboring streams $\vec{x} = (x_1, \dots, x_n)$ and $\vec{x}' = (x'_1, \dots, x'_n)$ that differ on one update we have that $\mathcal{A}(\vec{x}) \approx_{(\varepsilon, \delta)} \mathcal{A}(x')$





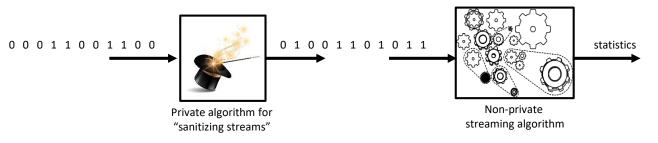


- For a predefined family of queries Q, a "streaming sanitizer" is a DP algorithm whose input is a stream S and its output is a stream \widehat{S} such that for every $q \in Q$ we have $\frac{1}{|S|} \sum_{x \in S} q(x) \approx \frac{1}{|\widehat{S}|} \sum_{x \in S} q(\widehat{x})$
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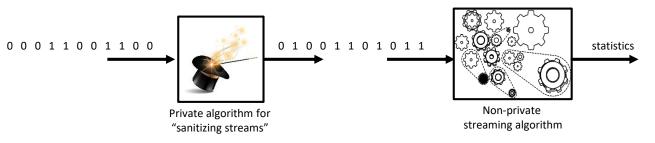


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- Construct a streaming sanitizer as follows:
 - 1) Let **D** denote the next **m** items
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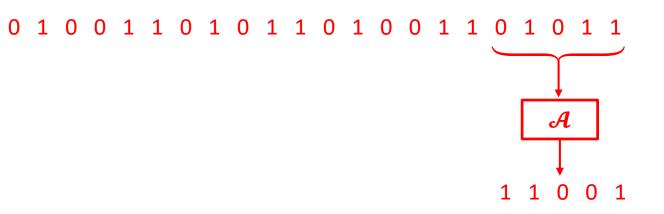
Idea 1: Synthetic streams

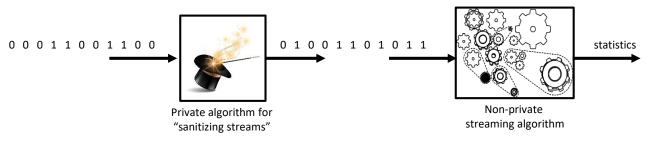


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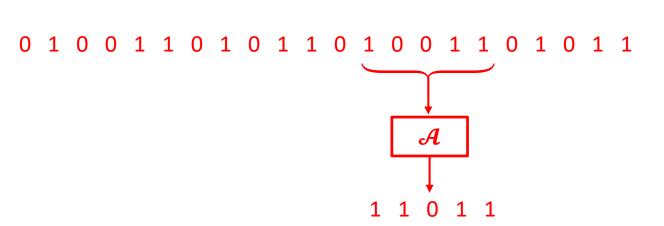


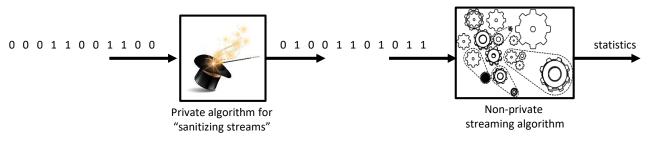
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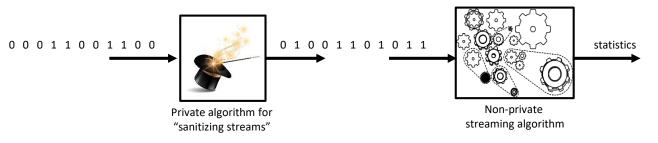


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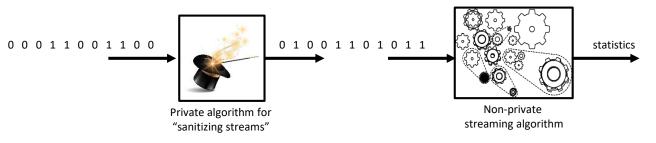




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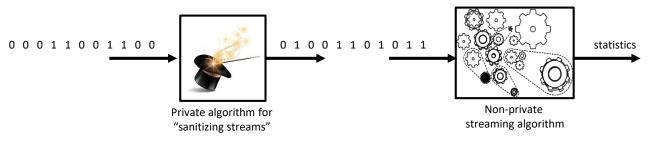


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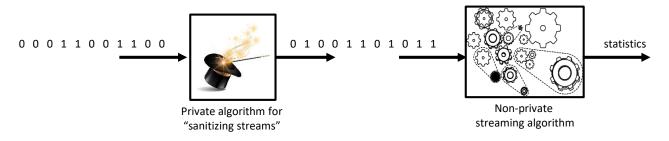
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Privacy analysis:

- We apply \mathcal{A} on disjoint portions of the input
- So no need for composition and privacy follows from *A*

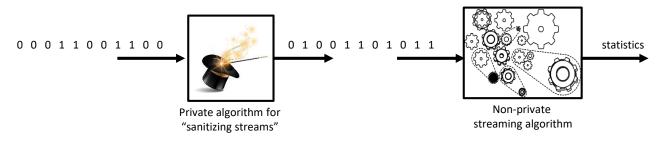
Utility analysis:

Since we aim for <u>relative</u> error, the error do not accumulate



- The point here is that our space does not depend directly on the length of the stream $m{n}$
- Our space equals to the space of the sanitizer *A*, which is independent of *n*, and the space of the non-private streaming algorithm

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Example where this is useful: Quantile estimation

- Items in the stream are numbers $x_1, x_2, \dots, x_n \in [0, 1]$
- The goal is, at the end of the stream, to get approximations for all quantiles of the data
- E.g., at the end of the stream we want to learn 9 numbers $y_1, y_2, ..., y_9 \in [0, 1]$ such that for every ℓ we have $|\{i: y_\ell \le x_i \le y_{\ell+1}\}| \approx \frac{n}{10}$

(this works well because we have very efficient "offline sanitizers" for this problem)

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Updates are bits and we want to estimate their sum

- Simple solution: Store the sum in memory using log *n* bits
 - Can we maintain a counter using smaller space?

Morris 78

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Step 1:

- Initialize estimate $\widehat{m{\textit{C}}}=m{0}$

— Given an update $x_i = 1$ flip a coin and increment \widehat{C} only if coin is heads

- We expect that $\widehat{C} \approx C/2$ where C is the true value
- The good: We still know *C* (approximately) while storing only a smaller number
- The bad: We saved only 1 bit (and also this has large variance, but let's ignore it...)

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Observe: The outcome distribution of the algorithm depends only on *C*

Morris 78

A Private Algorithm for the Counter Problem

[Dwork, Naor, Pitassi, Rothblum, Yekhanin]

• We can design a private variant as follows (informal):

— Sample $Y \sim \text{Lap}\left(\frac{1}{\varepsilon}\right)$

- Run Morris' counter on a modified stream:
 - If Y < 0 then ignore the first |Y| ones in the stream</p>
 - If *Y* ≥ 0 then add *Y* ones before the stream begins
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- The outcome distribution if a function of (C + Y), satisfying privacy by post-processing
- This idea is useful for other streaming problems

Example in the context of the counter problem: Counting the number of people who viewed my YouTube video

Streaming/online settings Today's Outline



2. Privacy under continual observation

[Dwork, Naor, Pitassi, Rothblum]

Modified problem – Counter with continual reports:

- On every time $t \in [n]$
 - —We get a bit $x_t \in \{0, 1\}$

—Need to respond with an approximation \hat{c}_i for $c_i = \sum_{i=1}^t x_i$

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Algorithm \mathcal{A} is (ε, δ) -DP for this problem if for any two neighboring streams $\vec{x} = (x_1, \dots, x_n)$ and $\vec{x}' = (x'_1, \dots, x'_n)$ that differ on one update we have that $\mathcal{A}(\vec{u}) \approx_{(\varepsilon,\delta)} \mathcal{A}(\vec{u}')$

Remarks:

- Observe that now $\mathcal{A}(\vec{x})$ is a vector of length m
- This problem is interesting regardless of space, so let's forget about space from now on
- Sanity check: Is the previous algorithm private w.r.t. this definition?

[Dwork, Naor, Pitassi, Rothblum]

Naïve attempts at solving the problem:

1) "LDP style": Every time $t \in [n]$ we release $\hat{x}_t = x_t + \text{Lap}\left(\frac{1}{\epsilon}\right)$

—This would maintain privacy, but sum of n noises accumulates to $pprox \sqrt{n}/arepsilon$

2) Using composition: Every time $t \in [n]$ we release $\hat{c}_t = (\sum_{i=1}^t x_t) + \text{Lap}(b)$ —We would need $b \approx \sqrt{n}/\epsilon$ due to composition

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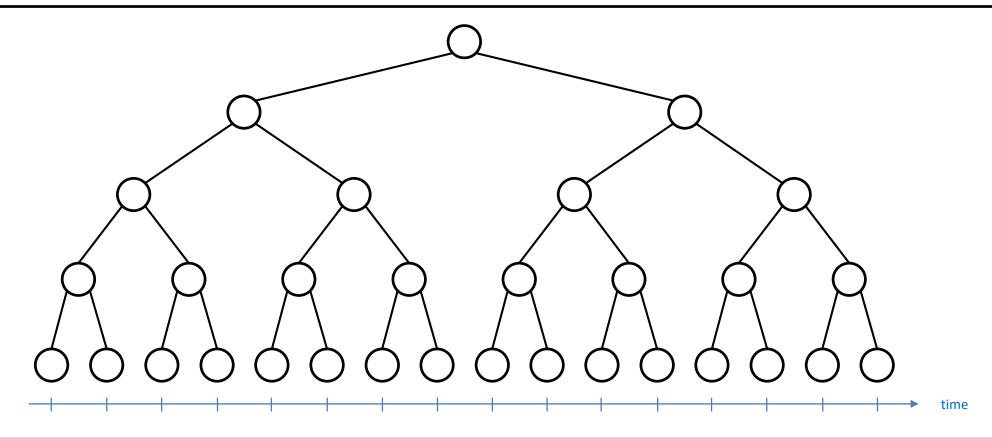
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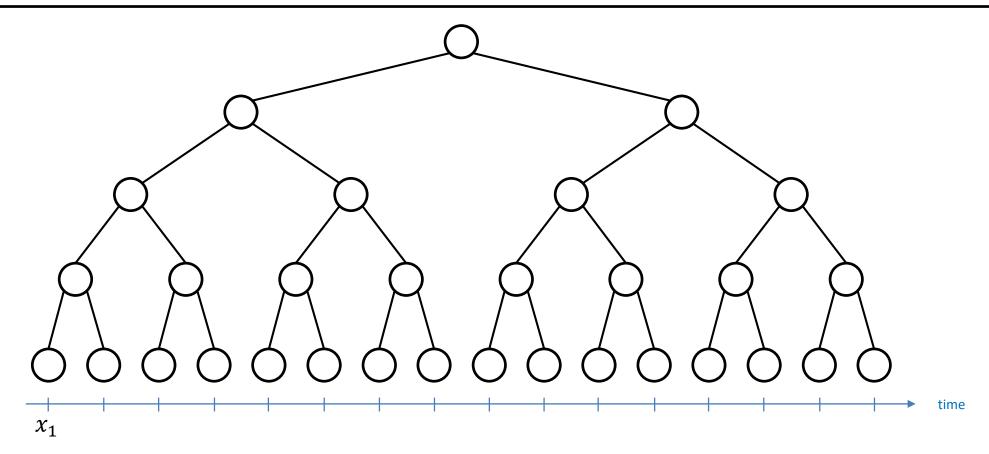
How can we do better?

- Observe: in solution (1) every user affects only one computation, so no need for composition, but the noises accumulate. In solution (2) we do not accumulate noises, but each one must be big to account for composition over *n* computations
- We want something in between

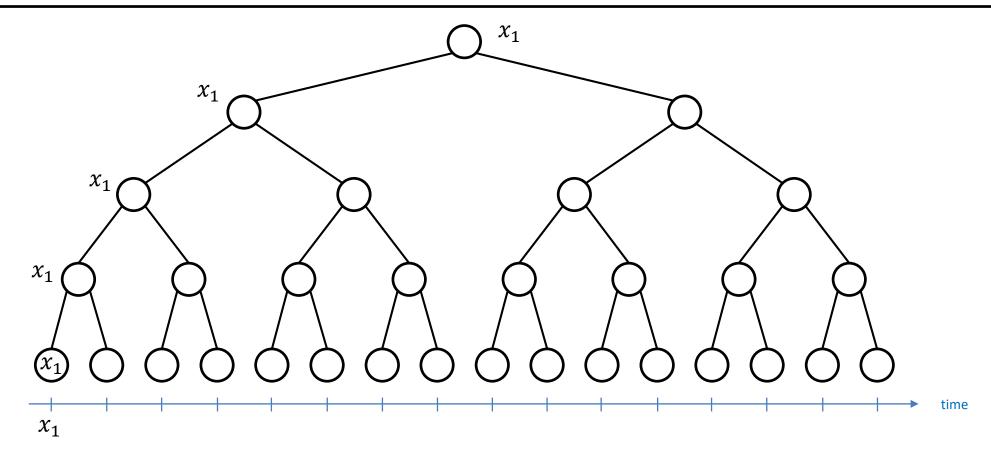
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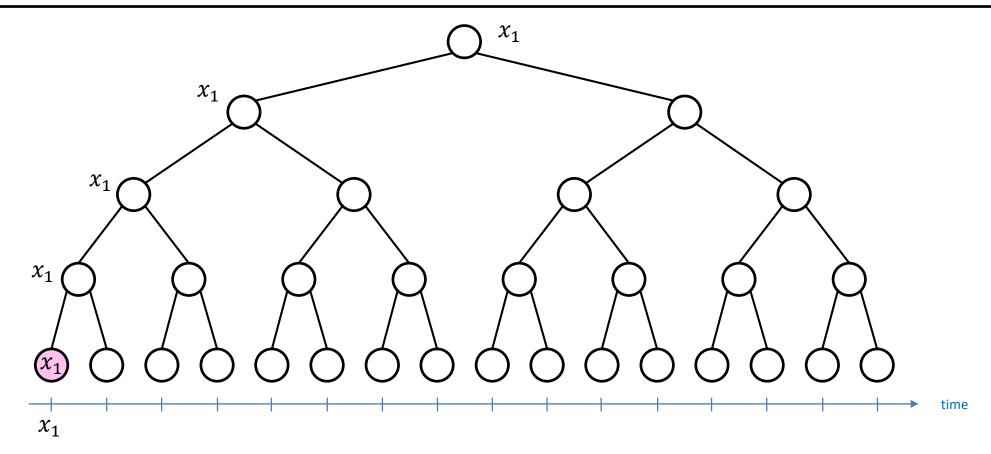
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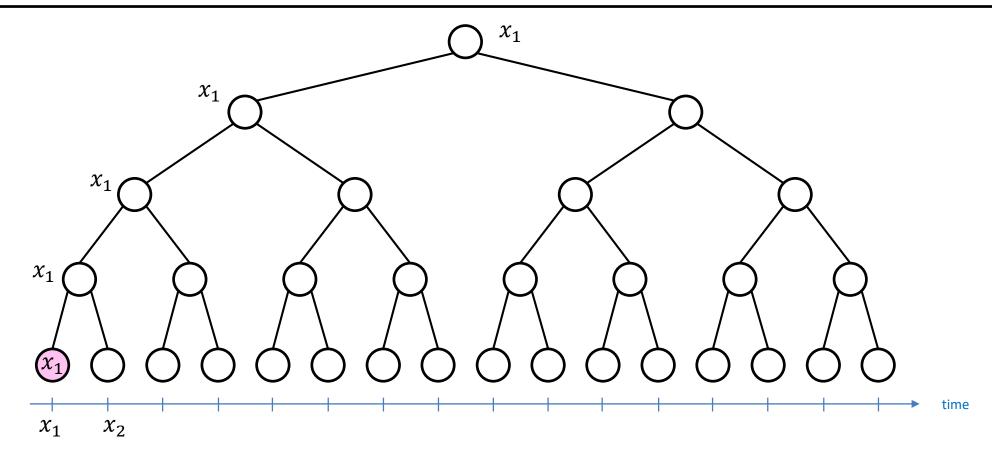
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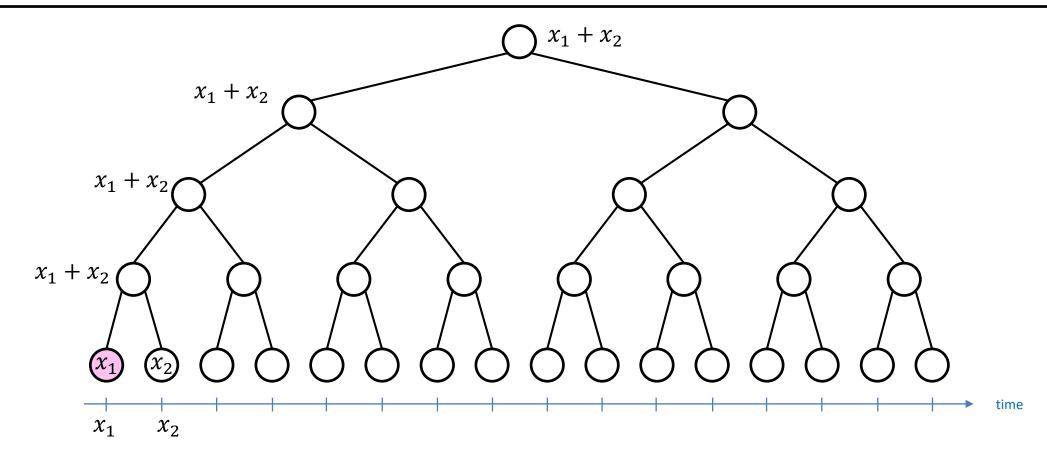
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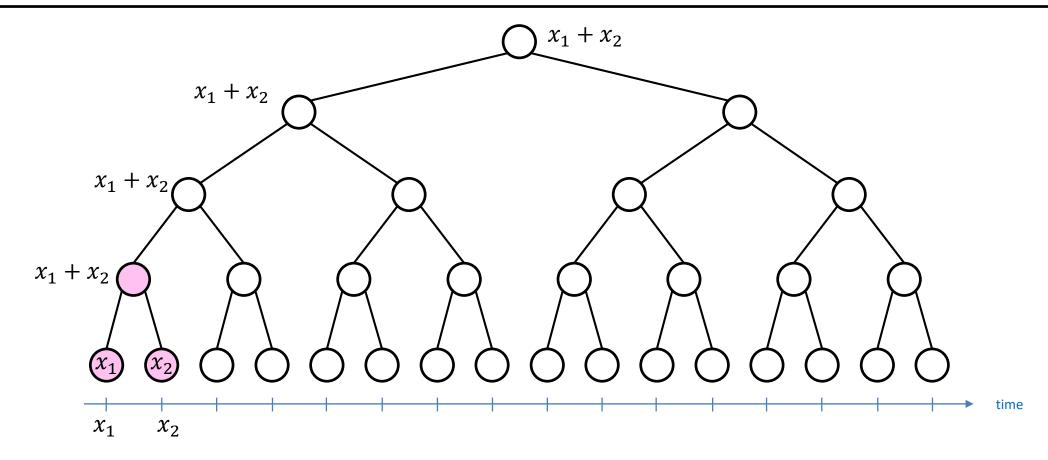
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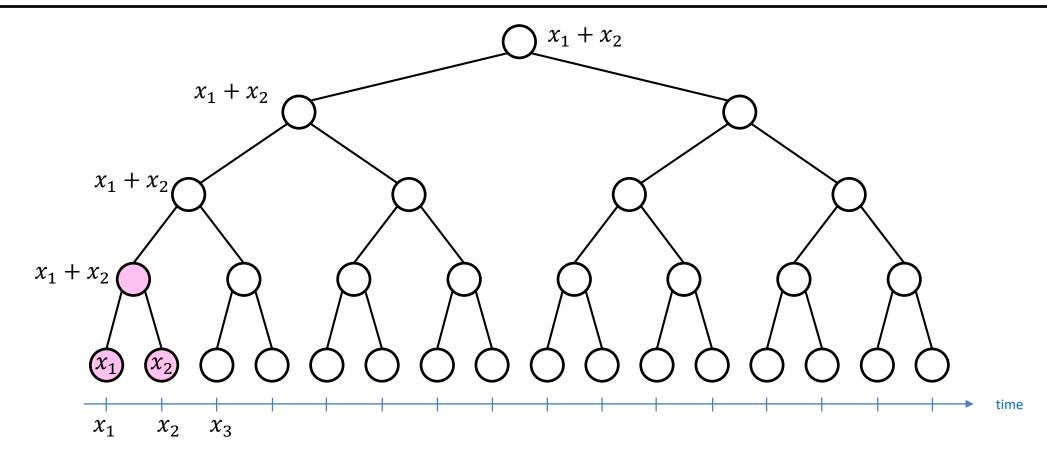
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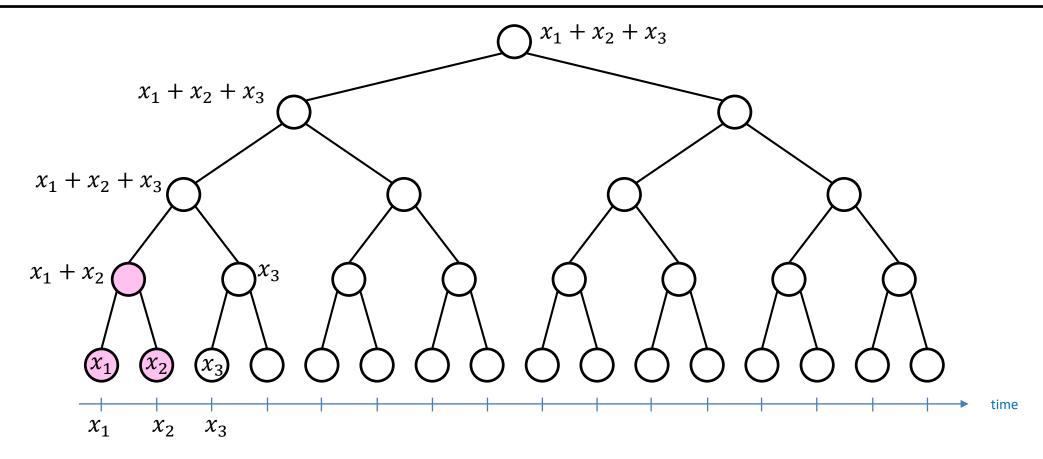
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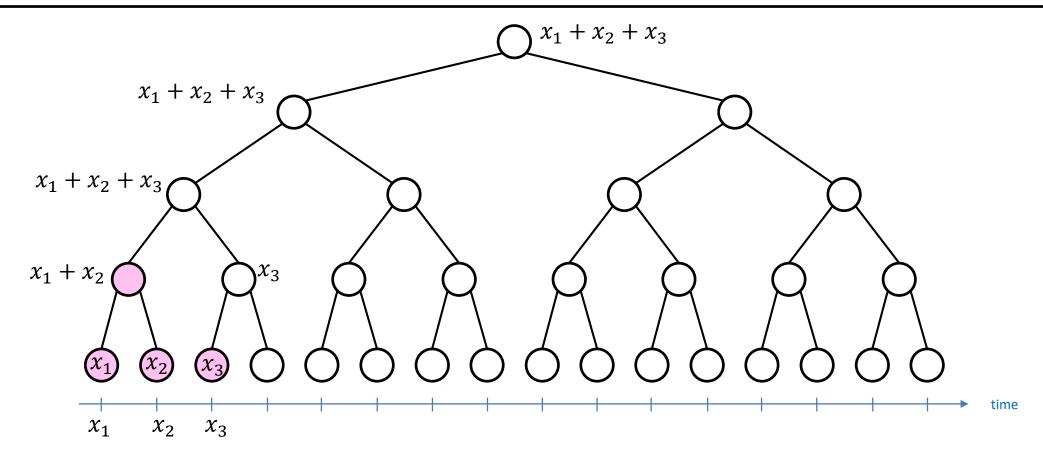
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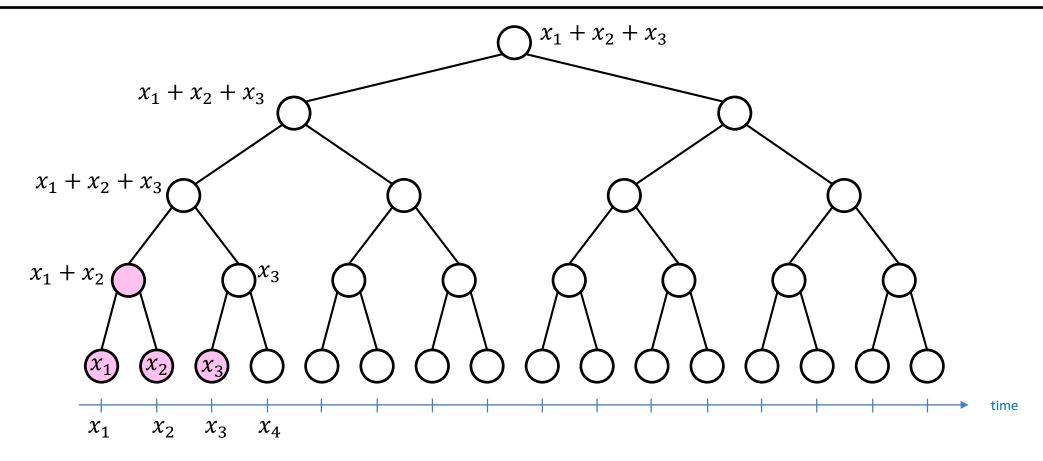
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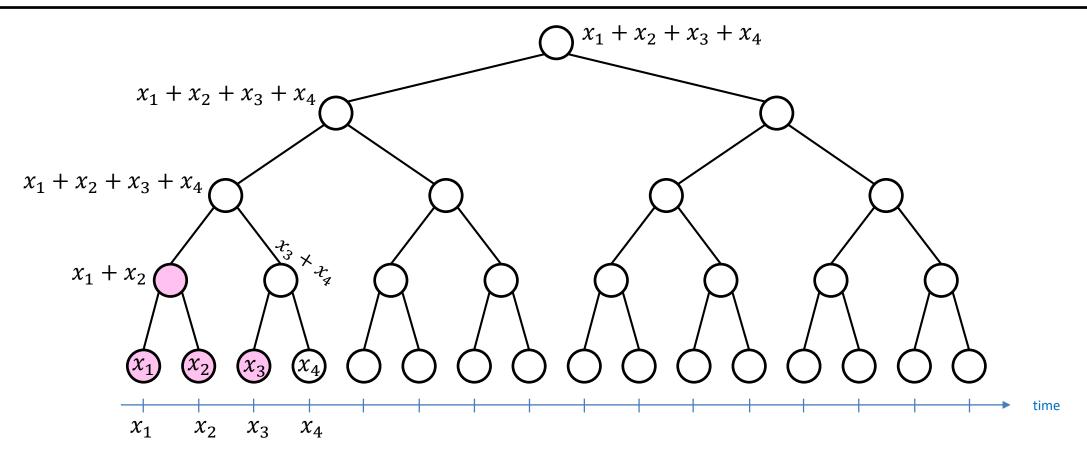
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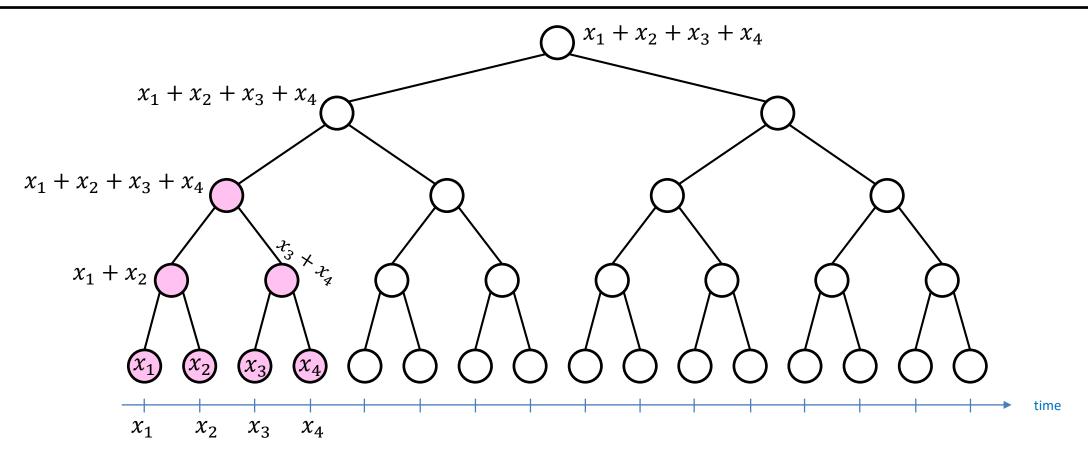
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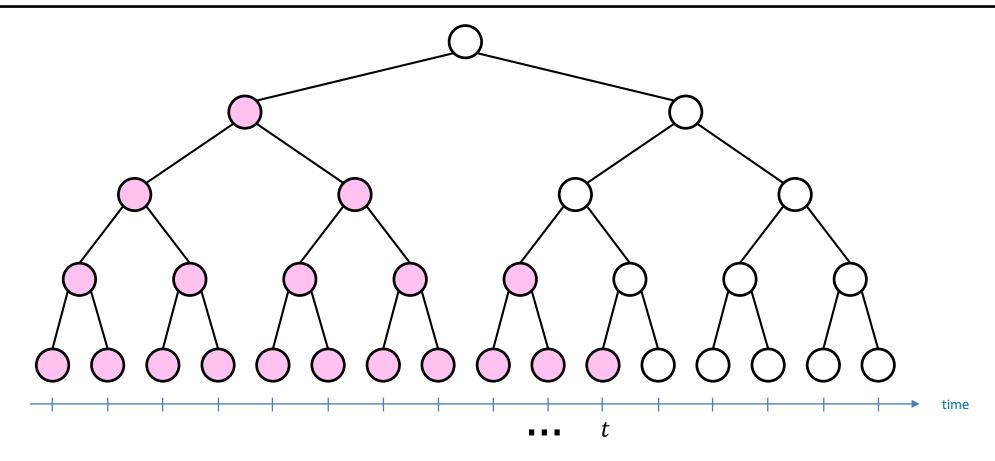
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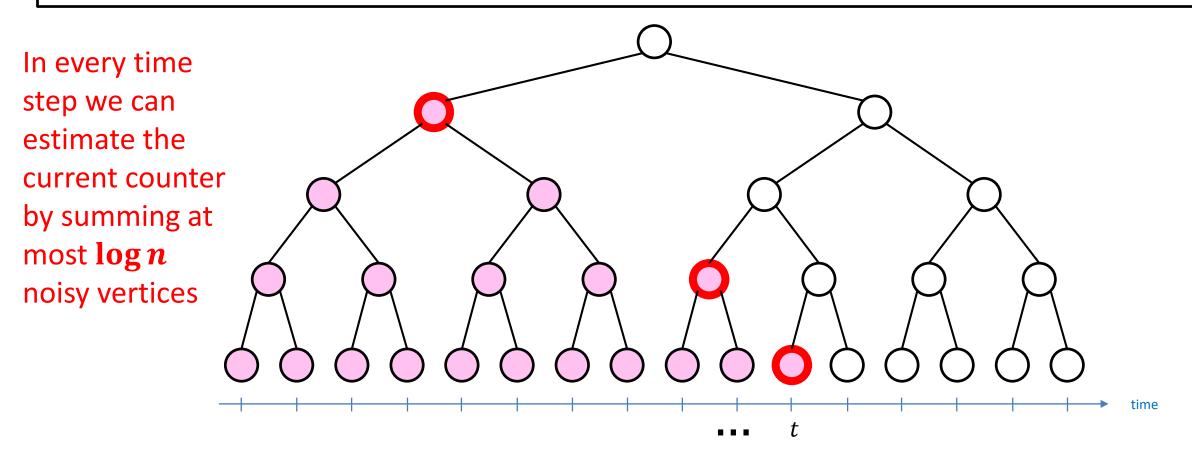
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- 3) In time t we get x_t and add it to all the nodes along the path from leaf t till the root
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- Once a subtree is "full" then its root is never updated again
- Thus, we release the content of every node exactly once after adding Laplace noise
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<u>Utility analysis:</u>

- At any time *t* we can compute an estimated counter by summing at most log *n* nodes
- So we are only summing $\log n$ noises, each of magnitude $\approx \log n$
- Overall error is $\frac{\text{polylog } n}{\epsilon}$

[Dwork, Naor, Pitassi, Rothblum]

<u>**Thm:</u>** Every (1, 0)-DP algorithm for this problem must have error $\Omega(\log n)$ </u>

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- Suppose there is a private algorithm \mathcal{A} such that w.p. 2/3 all of its estimates are accurate to within error $\frac{\log n}{16}$ Construct a collection $H = \left\{ \vec{x}^{(1)}, \vec{x}^{\left(\frac{\log n}{4}\right)}, \dots \right\}$ of input sequences where $\vec{x}^{(i)} = \begin{pmatrix} 0, 0, \dots, 0, \underbrace{1, 1, 1, \dots, 1}_{\frac{\log n}{4} \text{ ones from time } i}, 0, \dots, 0 \end{pmatrix}$

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- The algorithm has error at most $\frac{\log n}{16}$ so if we run it on input $\vec{x}^{(i)}$ then:
 - Before time *i* the estimation must be at most $\frac{\log n}{16}$ - After time $i + \frac{\log n}{4}$ the estimation must be at least $\frac{3 \log n}{16}$
- Hence, a sequence of answers cannot by good for more than one $\vec{x}^{(i)}$

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- Hence, a sequence of answers cannot by good for more than one $\vec{x}^{(i)}$ and for every $i \neq \ell$ we have

$$\frac{2}{3} \le \Pr\begin{bmatrix} \mathcal{A}(\vec{x}^{(i)}) \text{ returns} \\ \text{good answers} \\ \text{for } \vec{x}^{(i)} \end{bmatrix} \le e^{2\frac{\log n}{4}} \cdot \Pr\begin{bmatrix} \mathcal{A}(\vec{x}^{(\ell)}) \text{ returns} \\ \text{good answers} \\ \text{for } \vec{x}^{(i)} \end{bmatrix} = \sqrt{n} \cdot \Pr\begin{bmatrix} \mathcal{A}(\vec{x}^{(\ell)}) \text{ returns} \\ \text{good answers} \\ \text{for } \vec{x}^{(i)} \end{bmatrix}$$

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- Suppose there is a private algorithm \mathcal{A} such that w.p. 2/3 all of its estimates are accurate to within error $\frac{\log n}{16}$
- Suppose there is a private algorithm of such that $m_{p} = i = j = 1$. Construct a collection $H = \left\{ \vec{x}^{(1)}, \vec{x}^{\left(\frac{\log n}{4}\right)}, \dots \right\}$ of input sequences where $\vec{x}^{(i)} = \left(\begin{array}{c} 0, 0, \dots, 0, \\ 0, \dots, 0, \\ \frac{\log n}{4} \text{ ones from time } i \end{array} \right)$
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[Jain, Raskhodnikova, Sivakumar, Smith 2021]

Recall the XOR-sum problem:

- The input of every user i is a pair $(j_i, b_i) \in \{1, 2, \dots, n\} \times \{0, 1\}$
- The goal: estimate $\sum_{j=1}^{n} \bigoplus_{i:j_i=j} b_i$

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Informal theorem: Any continual-DP algorithm for this problem must have error $\Omega(\text{poly } n)$

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Proof:

- An algorithm *A* for this problem can be used to answer <u>many</u> "Hamming distance queries"; contradiction...
- Specifically, given input dataset $X = (x_1, ..., x_{\sqrt{n}})$, feed $(1, x_1), ..., (\sqrt{n}, x_{\sqrt{n}})$ to algorithm \mathcal{A}
- Then, given a query $Y = (y_1, ..., y_{\sqrt{n}})$:
 - Feed $(1, y_1), ..., (\sqrt{n}, y_{\sqrt{n}})$ to algorithm \mathcal{A} to obtain an answer z
 - Feed $(1, y_1), \dots, (\sqrt{n}, y_{\sqrt{n}})$ to algorithm \mathcal{A} again
- After $\approx \sqrt{n}$ queries (total input length n) we can reconstruct X contradicting the privacy of \mathcal{A}

Streaming/online settings Today's Outline

Private streaming algorithms
Privacy under continual observation